Errata for Deep Inertial Poser: Learning to Reconstruct Human Pose from Sparse Inertial Measurements in Real Time

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This document contains errata in the original paper Deep Inertial Poser: Learning to Reconstruct Human Pose from Sparse Inertial Measurements in Real Time.

Errata 1:

The frame conversion described in Equation 8 was wrong in the earlier version of the paper

\[ R_{TB}^t = R_{TS}^t R_{TS}^{-1} R_{SB} \]

and the right one should be

\[ R_{TB}^t = R_{TS}^t R_{SB} = R_{TS}^{-1}(R_{BS}) \]

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